

# Temporally Annotated Extended Logic Programs

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**Abstract**— Extended logic programs (ELPs) are a set of logic rules with strong negation  $\neg$  allowed in the bodies or head of the rules and weak negation  $\sim$  allowed in the bodies of the rules. ELPs enable for various forms of reasoning that cannot be achieved by definite logic programs. Answer Set Programming provides a widely acceptable semantics for ELPs. However, ELPs do not provide information regarding the temporal intervals that derived ELP literals or weakly negated ELP literals are valid. In this paper, we associate ELP rules with their validity temporal interval, resulting in a *temporally annotated logic program*. A ground temporal literal has the form  $L:i$ , where  $L$  is a ground ELP literal or weakly negated ELP literal and  $i$  is a temporal interval. We define (simple) entailment and maximal entailment of a ground temporal literal  $L:i$  from a temporally annotated logic program  $C$ . Both kinds of entailment are based on Answer Set Programming. Additionally, we provide an algorithm that for an ELP literal or a weakly negated ELP literal  $L$  returns a list with all temporal intervals  $i$  such that a temporally annotated logic program  $C$  maximally entails  $L:i$ . Based on this algorithm, the answer of various kinds of temporal queries can be provided.

**Keywords**- *Extended logic programs; validity temporal intervals; temporal inference; query answering.*

## I. INTRODUCTION

Extended logic programs (ELPs) are a set of logic rules with strong negation  $\neg$  allowed in the bodies or head of the rules and weak negation  $\sim$  allowed in the bodies of the rules [1]. ELP rules are assumed to be valid at the time of their evaluation but no historical information is derived as it is not known if these rules were valid in the past. However, each ELP rule is usually valid at a certain interval of time. In this paper, we associate ELP rules with their validity temporal interval. Thus, derived ELP literals and weakly negated ELP literals are associated with the temporal intervals at which they are valid. A temporal interval has the form  $[t_1, t_2]$ , where  $t_1, t_2$  are time points s.t.  $t_1 \leq t_2$  and it includes all time points  $t$  s.t.  $t_1 \leq t \leq t_2$ . In this paper, time points are years but they can also be dates, date times, etc. In general, we assume that the set of time points is a discrete linearly ordered domain that can be mapped to the set of integers through a bijective mapping.

In particular, ELP logic rules, associated with their validity temporal interval, form a *temporally annotated logic program*. A ground temporal literal has the form  $L:i$ , where  $L$  is a ground ELP literal or weakly negated ELP literal and  $i$  is a temporal interval. We define (simple) entailment of a ground temporal literal  $L:i$  from a temporally annotated logic program  $C$  expressing that according to  $C$ ,  $L$  is true during all time points within  $i$ . We define maximal entailment of a ground temporal literal  $L:i$  from a temporally annotated logic program  $C$ , expressing that according to  $C$ ,  $L$  is true during all

time points within  $i$  but  $L$  is not true at the time point before  $i$  and at the time point after  $i$ . Both kinds of entailment are based on Answer Set Programming [1]. The complexities of simple and maximal entailment of ground temporal literals are provided showing that simple temporal entailment is not harder than entailment of a ground ELP literal from an ELP logic program, based on Answer Set Programming.

We provide an algorithm that for an ELP literal or a weakly negated ELP literal  $L$  returns a list with all temporal intervals  $i$  such that a temporally annotated logic program  $C$  maximally entails  $L:i$ . Based on this algorithm, the answer of various kinds of temporal queries can be provided. For example, the user may request the maximal temporal intervals that a number of ELP literals or weakly negated ELP literals hold concurrently within a temporal interval of interest. Additionally, the user may request the maximal temporal intervals that a number of ELP literals or weakly negated ELP literals hold, provided that these intervals are associated with complex relations concerning their duration, start and end points. In particular, we define four types of simple temporal queries. Additionally, we define a complex temporal query as a conjunction of simple temporal queries and a *filter* condition that provides for various kinds of checks regarding the duration, start and end points of the temporal intervals returned by the query. The filter condition can express any combination of Allen's interval algebra relations [2].

To the best of our knowledge, there is no work concerning entailment from ELP rules associated with their validity temporal intervals. The rest of the paper is organized as follows: In Section II, we define temporally annotated logic programs and entailment of temporal literals. Additionally, we provide an algorithm that for an ELP literal or weakly negated ELP literal  $L$  returns a list with all temporal intervals  $i$  such that a temporally annotated logic program  $C$  maximally entails  $L:i$ . In Section III, we define various kinds of temporal queries and their answers. In Section IV, we present related work. Finally, Section V concludes the paper.

## II. TEMPORALLY ANNOTATED LOGIC PROGRAMS & ENTAILMENT

In this section, we define temporally annotated logic programs and entailment of temporal literals.

We consider a vocabulary  $V = \langle Pred, Const \rangle$ , where  $Pred$  is a set of predicate symbols and  $Const$  is a set of constants. We consider a set of variable symbols  $Var$ . Variables are preceded by the question mark symbol "?". Additionally, we consider a maximal temporal interval  $[t_{min}, t_{max}]$ , within which all temporal inferences are made.

**Definition 1** [temporally annotated logic rule]

A *temporally annotated logic rule* over a vocabulary  $V$  is an ELP rule over  $V$  associated with a temporal interval  $i$ , i.e. it has the form  $i:r$  where  $r$  is an ELP rule and  $i=[t_1,t_2]$ , where  $t_1 \leq t_{min}$  and  $t_2 \leq t_{max}$ .

**Definition 2** [temporally annotated logic program]

A *temporally annotated logic program*  $C$  over a vocabulary  $V$  is a set of temporally annotated logic rules over  $V$ .

**Example 1** An example temporally annotated logic program  $C$  over  $V=\langle Pred, Const \rangle$ , where  $Pred$  are all predicates appearing in  $C$  and  $Const$  are all the constants appearing in  $C$ , is the following (we consider  $t_{min}=1988$  and  $t_{max}=2012$ ):

- [1990,1994]:  $has\_job(Mary, Hairdresser)$ .
- [1995,2002]:  $has\_job(Mary, Secretary)$ .
- [2006,2009]:  $has\_job(Mary, Hairdresser)$ .
- [2001,2003]:  $has\_job(Peter, Garbage\_collector)$ .
- [2005,2008]:  $has\_job(Peter, Builder)$ .
- [1980,1992]:  $heavy\_job(Hairdresser)$ .
- [1980,2000]:  $heavy\_job(Garbage\_collector)$ .
- [1999,2012]:  $heavy\_job(Builder)$ .
- [1988, 1991]:  $vacation\_days(?x,29) \leftarrow has\_job(?x,?y), heavy\_job(?y)$ .
- [1992, 2012]:  $vacation\_days(?x,27) \leftarrow has\_job(?x,?y), heavy\_job(?y)$ .
- [1988, 1991]:  $vacation\_days(?x,25) \leftarrow has\_job(?x,?y), \sim heavy\_job(?y)$ .
- [1992, 2012]:  $vacation\_days(?x,22) \leftarrow has\_job(?x,?y), \sim heavy\_job(?y)$ .

Predicate  $has\_job(x,y)$  expresses that  $x$  has as job  $y$ . Predicate  $heavy\_job(x)$  expresses that  $x$  is a heavy and unhealthy job. Predicate  $vacation\_days(x,y)$  expresses that  $x$  is entitled to  $y$  vacations days per year.

*Convention:* In the sequel, by  $C$ , we will denote a temporally annotated logic program and, by  $V=\langle Pred, Const \rangle$ , we will denote the vocabulary of  $C$ .

Below, we define the temporal projection of  $C$  at a certain time point  $t$ .

**Definition 3** [temporal projection]

The temporal projection of  $C$  at a time point  $t$  is the extended logic program  $C(t)=\{r \mid i:r \in C \text{ and } t \in i\}$ .

**Example 2** Consider the temporally annotated logic program  $C$  of Example 1. Then,  $C(1994)$  is the following extended logic program:

- $has\_job(Mary, Hairdresser)$ .
- $heavy\_job(Garbage\_collector)$ .
- $vacation\_days(?x,27) \leftarrow has\_job(?x,?y), heavy\_job(?y)$ .
- $vacation\_days(?x,22) \leftarrow has\_job(?x,?y), \sim heavy\_job(?y)$ .

A temporal literal over  $V$  has the form  $L:i$ , where  $L$  is an ELP literal or a weakly negated ELP literal over  $V$  and  $i$  a temporal interval or variable, called *temporal variable*.

Let  $P$  be an extended logic program of a vocabulary  $V=\langle Pred, Const \rangle$  and  $L$  be an ELP literal or a weakly negated ELP literal over  $V$ , we write  $P \models^{ASP} L$  if the grounded version of  $P$  over the constants in  $Const$  entails  $L$  under Answer Set Programming [1].

**Definition 4** [temporal entailment]

We say that  $C$  (*simply*) *entails* a ground temporal literal  $L:i$ , denoted by  $C \models L:i$ , if for all  $t \in i$ ,  $C(t) \models^{ASP} L$ . We say that  $C$  *maximally entails* a temporal literal  $L:[t_1,t_2]$ , denoted by

$C \models_{max} L:[t_1,t_2]$ , if

1.  $C \models L:[t_1,t_2]$ ,
2. if  $t_1 > t_{min}$  then  $C(t_1-1) \not\models^{ASP} L$ , and
3. if  $t_2 < t_{max}$  then  $C(t_2+1) \not\models^{ASP} L$ .

**Example 3** Consider the temporally annotated logic program  $C$  of Example 1. Then,  $C \models vacation\_days(Mary,22):[2006,2008]$  and  $C \models_{max} vacation\_days(Mary,22):[2006,2009]$ . Additionally,  $C \models vacation\_days(Peter,27):[2006,2007]$  and  $C \models_{max} vacation\_days(Peter,27):[2005,2008]$ .

**Proposition 1** Let  $L:i$  be a ground temporal literal over  $V$ . Deciding if  $C \models L:i$  is:

1. co-NP-complete, in the case that  $C$  does not contain variables or the number of variables of each rule of  $C$  is less than a constant.
2. co-NEXPTIME-complete, in the general case.

Note that entailment of a ground ELP literal from an ELP program  $P$ , under Answer Set Programming is (i) co-NP-complete, in the case that  $P$  does not contain variables or the number of variables of each rule of  $P$  is less than a constant and (ii) co-NEXPTIME-complete, in the general case [3]. Therefore, entailment of a ground temporal literal from a temporally annotated logic program does not increase the computational complexity over Answer Set Programming.

Now, we provide a few definitions. Let  $i=[t_1, t_2]$  be a temporal interval. We define  $start(i)=t_1$  and  $end(i)=t_2$ . Let  $L$  be an ELP literal or a weakly negated ELP literal, we denote by  $pred(L)$ , the predicate appearing in  $L$ . Let  $r$  be an ELP rule. We denote by  $Head(r)$ , the head of  $r$ .

Below, we present the algorithm  $FindMaximalIntervals(C, L)$  that, for an ELP literal or a weakly negated ELP literal  $L$ , returns a list with all temporal intervals  $i$  such that  $C \models_{max} L:i$ . This algorithm calls the algorithm  $GetIntervals(C,p)$  which returns a list of the maximal temporal intervals  $i$  that define predicate  $p$ , i.e. for all  $t \in i$ ,  $p$  appears in the head of a rule of  $C(t)$ . The list of returned temporal intervals  $i$  is sorted by  $start(i)$ .

Algorithm 1  $GetIntervals(C,p)$ , where  $p \in Pred$ , first gets all intervals  $i$  s.t. there exist rule  $i:r \in C$  with  $pred(Head(r))=p$ . Then, it orders these intervals  $i$  based on  $start(i)$  and puts them in a list  $IL$ .

Afterwards, it fetches intervals from  $IL$  in the stored order and combines the intervals that overlap or are consecutive, creating maximal intervals that puts them in a new list  $IL'$ . Finally, it returns  $IL'$ .

**Algorithm 1** GetIntervals(C,p)

*Input:* a temporally annotated logic program  $C$  and a predicate  $p \in Pred$

*Output:* a sorted list of the maximal temporal intervals  $i$  that define  $p$

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Let  $S = \{i \mid i:r \in C \text{ and } p = pred(Head(r))\}$ .  
If  $S = \{\}$  then return(empty list).  
Order intervals  $i \in S$  by  $start(i)$  and put them in list  $IL$ .  
Let  $IL'$  be the empty list.  
Get first interval  $i$  from  $IL$ .  
 $current\_start = start(i)$ .  
 $current\_end = end(i)$ .  
For each interval  $i$  taken in sequence from the list  $IL$  do  
If  $start(i) \leq current\_end + 1$  and  $end(i) > current\_end$  then  
 $current\_end = end(i)$ .  
If  $start(i) > current\_end + 1$  or  $i$  is the last interval in  
 $IL$  then  
Add at the end of  $IL'$  the temporal interval  
 $[current\_start, current\_end]$ .  
 $current\_start = start(i)$ .  
 $current\_end = end(i)$ .  
If  $start(i) > current\_end + 1$  and  $i$  is the last interval in  $IL$   
then  
Add at the end of  $IL'$  the temporal interval  
 $[start(i), end(i)]$ .  
EndFor  
return( $IL'$ ).
```

**Example 4** Consider the temporally annotated logic program  $C$  of Example 1. Then,  $GetIntervals(C, has\_job)$  returns the list  $[[1990,2003], [2005,2009]]$ .

Algorithm 2  $FindMaximalIntervals(C,L)$ , where  $L$  is an ELP literal or a weakly negated ELP literal over  $V$ , first calls algorithm  $GetIntervals(C, pred(L))$  which returns a list  $IL$  of maximal intervals  $i$  that define  $pred(L)$ , ordered by  $start(i)$  (line 2). Assume that  $IL$  is the empty list (lines 3-7). If  $L$  is a weakly negated literal then the algorithm returns the list containing  $[t_{min}, t_{max}]$ . This is because in this case  $C \models_{max} L: [t_{min}, t_{max}]$ . Otherwise, the algorithm returns the empty list. This is because in this case, there is no interval  $i$  s.t  $C \models_{max} L:i$ . If  $IL$  is not the empty list then the algorithm fetches the first interval  $i$  of  $IL$  and if  $L$  is a weakly negated ELP literal and  $start(i) \neq t_{min}$  then it puts the interval  $[t_{min}, start(i)-1]$  in a new list  $IL'$  (line 11). This is because for all time points  $t \in [t_{min}, start(i)-1]$ , it holds that  $C(t) \models^{ASP} L$ . Then, it fetches each interval  $[t_s, t_e]$  from  $IL$  in the stored order.

Afterwards, it examines each time point  $t \in [t_s, t_e]$  and creates maximal temporal intervals  $i$  within  $[t_s, t_e]$  such that for each  $t' \in i$ , it holds that  $C(t) \models^{ASP} L$  (lines 13-21). These intervals are stored in order in  $IL'$  with the difference that if the first of these intervals is consecutive with the previous interval in  $IL'$  then it combines these. Note that if  $[t_s, t_e]$  is the last temporal interval in  $IL$ ,  $L$  is a weakly negated literal, and  $t_e < t_{max}$  then, for each  $t \in [t_e+1, t_{max}]$ , it holds that  $C(t) \models^{ASP} L$ . Thus, if  $C(t_e) \models^{ASP} L$  then it combines interval  $[t_e+1, t_{max}]$  with the last interval in  $IL'$  (line 25), otherwise it adds interval  $[t_e+1, t_{max}]$  to the end of  $IL'$  (line 27). If  $[t_s, t_e]$  is not the last

temporal interval in  $IL$  and  $L$  is a weakly negated literal then (i) if  $C(t_e) \models^{ASP} L$  and  $[t'_s, t_e]$  is the last interval in  $IL'$  then it replaces it by the interval  $[t'_s, t''_s-1]$  (line 31) and (ii) if  $C(t_e) \not\models^{ASP} L$  then it adds  $[t_e+1, t''_s-1]$  to  $IL'$  (line 33), where  $[t''_s, t''_e]$  is the next to  $[t_s, t_e]$  interval in  $IL$ . This, is because for all  $t \in [t_e+1, t''_s-1]$ , it holds that  $C(t) \models^{ASP} L$ . Then, this process continues until all intervals  $[t_s, t_e]$  from  $IL$  are fetched. In the latter case, the temporal interval list  $IL'$  is returned.

**Algorithm 2** FindMaximalIntervals(C,L)

*Input:* a temporally annotated logic program  $C$  and an ELP literal or a weakly ELP literal  $L$  over  $V$

*Output:* a sorted list of maximal temporal intervals  $i$  s.t. for each  $t \in i$ ,  $C(t) \models^{ASP} L$

- (1)  $flag = TRUE$ .
- (2)  $IL = GetIntervals(C, pred(L))$ .
- (3) If  $IL$  is the empty list then
- (4) If  $L$  is a weakly negated ELP literal then
- (5) return(a list containing  $[t_{min}, t_{max}]$ ).
- (6) else
- (7) return(empty list).
- (8) Let  $IL'$  be the empty list.
- (9) Let  $i$  be the first item in  $IL$ .
- (10) If  $L$  is a weakly negated ELP literal and  $start(i) \neq t_{min}$  then
- (11) Add  $[t_{min}, start(i)-1]$  to the end of  $IL'$ .
- (12) For each interval  $[t_s, t_e]$  taken in sequence from the list  $IL$  do
- (13) For each time point  $t = t_s, \dots, t_e$  do
- (14) If  $C(t) \models^{ASP} L$  then
- (15) If  $IL'$  is not empty and  $flag = TRUE$  then
- (16) Take the last item  $[t'_s, t'_e]$  from  $IL'$  and replace it by  $[t'_s, t]$ .
- (17) else
- (18) Add interval  $[t, t]$  to the end of  $IL'$ .
- (19) else /\*  $C(t) \not\models^{ASP} L$  \*/
- (20)  $flag = FALSE$ .
- (21) EndFor
- (22) If  $[t_s, t_e]$  is the last interval in  $IL$  then
- (23) If  $L$  is a weakly negated ELP literal and  $t_e \neq t_{max}$  then
- (24) If  $IL'$  is not empty and  $flag = TRUE$  then
- (25) Take the last item  $[t'_s, t'_e]$  from  $IL'$  and replace it by  $[t'_s, t_{max}]$ .
- (26) else
- (27) Add interval  $[t_e+1, t_{max}]$  to the end of  $IL'$ .
- (28) else /\*  $[t_s, t_e]$  is not the last interval in  $IL$  \*/
- (29) If  $L$  is a weakly negated ELP literal then
- (30) If  $IL'$  is not empty and  $flag = TRUE$  then
- (31) Take the last interval  $[t'_s, t'_e]$  from  $IL'$  and replace it by  $[t'_s, t''_s-1]$ , where  $[t''_s, t''_e]$  is the next interval to  $[t_s, t_e]$  in  $IL$ .
- (32) else
- (33) Add  $[t_e+1, t''_s-1]$  to the end of  $IL'$  where  $[t''_s, t''_e]$  is the next interval to  $[t_s, t_e]$  in  $IL$ .
- (34)  $flag = TRUE$ .

- (35) else /\*  $L$  is not a weakly negated ELP literal \*/  
(36) flag=FALSE.  
(37) EndFor  
(38) return(IL').

**Example 5** Consider the temporally annotated logic program  $C$  of Example 1. Then,  $FindMaximalIntervals(C, has\_job(Mary, Hairdresser))$  returns the list [[1990,1994], [2006, 2009]] and  $FindMaximalIntervals(C, \sim has\_job(Mary, Hairdresser))$  returns the list [[1988, 1989], [1995,2005], [2010,2012]].

Based on Algorithm 2, the following complexity results are derived.

**Proposition 2** Let  $L:i$  be a ground temporal literal over  $V$ . Deciding if  $C \models \max L:i$  is:

1. in  $P^{NP}$ , in the case that  $C$  does not contain variables or the number of variables of each rule of  $C$  is less than a constant, and
2. in  $P^{NEXPTIME}$ , in the general case.

We would like to note that we have investigated the case to define, for a temporally annotated logic program  $C$ , interpretations  $I$  containing temporal literals  $L:i$  s.t. if  $L:i, L:i' \in I$  then temporal intervals  $i, i'$  have no common time points and they are not consecutive. We can decide if  $I$  is an answer set of  $C$ , using techniques similar to Answer Set Programming, but now we work on temporal intervals and not on time points. Then,  $C \models L:[t_1, t_2]$ , if for all answer sets  $M$  of  $C$  it holds that  $M \models L:[t_1, t_2]$ . Additionally,  $C \models_{\max} L:[t_1, t_2]$ , if (i) for all answer sets  $M$  of  $C$ , it holds that  $M \models L:[t_1, t_2]$ , (ii) there is an answer set  $M$  of  $C$  such that  $M \not\models L:[t_1-1, t_1-1]$ , and (iii) there is an answer set  $M$  of  $C$  such that  $M \not\models L:[t_2+1, t_2+1]$ . However, this technique has higher complexity and does not provides answer sets in the case that it exists a time point  $t$  such that  $C(t)$  has no (consistent) answer set.

### III. QUERY ANSWERING

Below, we define the queries that can be imposed to a temporally annotated logic program  $C$  over a vocabulary  $V = \langle Pred, Const \rangle$  and their answers.

First, we define the intersection of a set of temporal intervals. The intersection of the temporal intervals  $[t_1, t'_1], \dots, [t_n, t'_n]$  is the interval  $[\max(\{t_1, \dots, t_n\}), \min(\{t'_1, \dots, t'_n\})]$ , if  $\max(\{t_1, \dots, t_n\}) \leq \min(\{t'_1, \dots, t'_n\})$ . Otherwise, it is undefined.

A simple temporal query of type 1 has the form  $SQ=L:i$ , where  $L:i$  is a temporal literal with  $i$  being a temporal interval. The answers of  $SQ$  w.r.t.  $C$ , denoted by  $Ans_C(SQ)$ , is the set of mappings  $v$  from the variables of  $L$  to  $Const$  s.t.  $C \models v(L:i)$ .

A simple temporal query of type 2 has the form  $SQ=L:?i$ , where  $L:?i$  is a temporal literal with  $?i$  being a temporal variable. The answers of  $SQ$  w.r.t.  $C$ , denoted by  $Ans_C(SQ)$ , is the set of mappings  $v$  from the variables of  $L$  to  $Const$  and from  $?i$  to the set of temporal intervals s.t  $C \models_{\max} v(L:?i)$ .

The answer to this type of queries can be provided using Algorithm 2.

A simple temporal query of type 3 has the form  $SQ=L_1:?i \wedge \dots \wedge L_n:?i$ , where  $L_i:?i$  is a temporal literal with  $?i$  being a temporal variable. The answers of  $SQ$  w.r.t.  $C$ , denoted by  $Ans_C(SQ)$ , is the set of mappings  $v$  s.t. if  $v_i \in Ans_C(L_i:?i)$ , for  $i=1, \dots, n$ , s.t.  $v_1, \dots, v_n$  coincide on the common variables of  $L_1, \dots, L_n$  then  $v$  coincides with  $v_i$  on the variables of  $L_i$ , for  $i=1, \dots, n$ , and maps  $?i$  to the intersection of the temporal intervals  $v_1(?i), \dots, v_n(?i)$ , if such intersection exists.

A simple temporal query of type 4 has the form  $SQ=L_1:?i \wedge \dots \wedge L_n:?i \wedge included(?i, [t_1, t_2])$ , where  $L_1:?i \wedge \dots \wedge L_n:?i$  is a simple temporal query of type 3 and  $t_1, t_2$  are time points. The answers of  $SQ$  w.r.t.  $C$ , denoted by  $Ans_C(SQ)$ , is the set of mappings  $v$  s.t. if  $u \in Ans_C(L_1:?i \wedge \dots \wedge L_n:?i)$  then  $v$  coincides with  $u$  on the variables of  $L_i$ , for  $i=1, \dots, n$ , and maps  $?i$  to the intersection of the temporal intervals  $u(?i)$  and  $[t_1, t_2]$ , if such intersection exists.

**Example 6** Consider the temporally annotated logic program  $C$  of Example 1. Consider the simple temporal query of type 1  $SQ=vacation\_days(Mary, ?x):[1994,2001]$ , requesting the vacations days that Mary is entitled to continuously during the temporal interval [1994,2001]. Then,  $Ans_C(SQ)$  is the mapping  $v$  s.t.  $v(?x)=22$ .

Consider the simple temporal query of type 2  $SQ=vacation\_days(Mary, ?x):?i$ , requesting the vacations days that Mary is entitled to and their maximal temporal intervals. Then,  $Ans_C(SQ)$  is the set of mappings (i)  $v_1$  s.t.  $v_1(?x)=29$  and  $v_1(?i)=[1990,1991]$ , (ii)  $v_2$  s.t.  $v_2(?x)=27$  and  $v_2(?i)=[1992, 1992]$ , (iii)  $v_3$  s.t.  $v_3(?x)=22$  and  $v_3(?i)=[1993, 2002]$ , and (iv)  $v_4$  s.t.  $v_4(?x)=22$  and  $v_4(?i)=[2006, 2009]$ .

Consider the simple temporal query of type 3  $SQ=has\_job(Mary, ?x):?i \wedge has\_job(Peter, ?y):?i$ , requesting the jobs of Mary and Peter and their common validity temporal intervals. Then,  $Ans_C(SQ)$  is the set of mappings (i)  $v_1$  s.t.  $v_1(?x)=Secretary$ ,  $v_1(?y)=Garbage\_collector$ , and  $v_1(?i)=[2001,2002]$  and (ii)  $v_2$  s.t.  $v_2(?x)=Hairdresser$ ,  $v_2(?y)=Builder$ , and  $v_2(?i)=[2006,2008]$ .

Consider the simple temporal query of type 4  $SQ=vacation\_days(Mary, ?x):?i \wedge included(?i, [1991, 2001])$ , requesting the vacations days that Mary is entitled to and their maximal temporal intervals, within the temporal interval of interest [1991, 2001]. Then,  $Ans_C(SQ)$  is the set of mappings (i)  $v_1$  s.t.  $v_1(?x)=29$  and  $v_1(?i)=[1991,1991]$ , (ii)  $v_2$  s.t.  $v_2(?x)=27$  and  $v_2(?i)=[1992,1992]$ , and (iii)  $v_3$  s.t.  $v_3(?x)=22$  and  $v_3(?i)=[1993,2001]$ .

A complex  $pt$ -query has the form  $CQ=SQ_1 \wedge \dots \wedge SQ_n \wedge filter$ , where  $SQ_i$  are simple temporal queries, each having a different temporal variable, and  $filter$  is an expression of the following EBNF grammar:

```
term:=duration(?i) | start(?i) | end(?i) | c,
      where ?i is a temporal variable and c is a decimal.
complex_term:= term | complex_term (+ | - | * | /)
              complex_term
comparison:= complex_term (< | > | = | ≤ | ≥ | ≠)
              complex_term
filter:= comparison | filter (∧ | ∨) filter,
```

such that each temporal variable appearing in *filter* appears in  $SQ_1 \wedge \dots \wedge SQ_n$ . The answers of *CQ* w.r.t. *C*, denoted by  $Ans_P(CQ)$ , is the set of mappings  $v$  s.t. (i) if  $u_i \in Ans_P(SQ_i)$ , for  $i=1, \dots, n$ , s.t.  $u_1, \dots, u_n$  coincide on the common variables of  $SQ_1, \dots, SQ_n$  then  $v$  coincides with  $u_i$  on the variables of  $SQ_i$ , for  $i=1, \dots, n$ , and (ii)  $v(filter)$  holds.

Note that all Allen's interval algebra relations and their combinations can be expressed by a *filter* expression. For example, the Allen's algebra relation *overlaps*(?*i*,?*j*) can be expressed by the filter  $(start(?i) < start(?j)) \wedge (start(?j) < end(?i))$ .

**Example 7** Consider the temporally annotated logic program *C* of Example 1. Consider the complex query  $CQ = has\_job(Mary, ?x):?i \wedge has\_job(Peter, ?y):?i' \wedge (start(?i) \leq end(?i')) \wedge (end(?i) \geq start(?i'))$ , requesting the job of Mary and its validity temporal interval and the job of Peter and its validity temporal interval, provided that these intervals have common time points. Then,  $Ans_C(SQ)$  is the set of mappings (i)  $v_1$  s.t.  $v_1(?x)=Secretary$ ,  $v_1(?i)=[1995,2002]$ ,  $v_1(?y)=Garbage\_collector$ , and  $v_1(?i')=[2001, 2003]$  and (ii)  $v_2$  s.t.  $v_2(?x)=Hairdresser$ ,  $v_2(?i)=[2006,2009]$ ,  $v_2(?y)=Builder$ , and  $v_2(?i')=[2005,2008]$ .

Consider the complex query

$$CQ = has\_job(Mary, ?x):?i \wedge has\_job(Peter, ?y):?i' \wedge \\ (start(?i) > start(?i')) \wedge (end(?i) < end(?i')) \wedge (end(?i) - start(?i) > 2) \vee \\ (start(?i') \geq start(?i)) \wedge (end(?i') \leq end(?i)) \wedge (end(?i') - start(?i') > 2) \vee \\ (start(?i) \leq start(?i')) \wedge (start(?i') \leq end(?i)) \wedge (start(?i') - end(?i) > 2) \vee \\ (start(?i') \leq start(?i)) \wedge (start(?i) \leq end(?i')) \wedge (start(?i) - end(?i') > 2)$$

requesting the job of Mary and its validity temporal interval and the job of Peter and its validity temporal interval, provided that these intervals have more than 2 common time points. Then,  $Ans_C(SQ)$  is the mapping  $v$  s.t.  $v(?x)=Hairdresser$ ,  $v(?i)=[2006,2009]$ ,  $v(?y)=Builder$ , and  $v(?i')=[2005,2008]$ .

#### IV. RELATED WORK

Below, we review related work.

In [4], the authors present a framework to incorporate temporal reasoning into RDFS [5][6]. The author associate RDF triples with their validity temporal interval and apply the RDFS inference rules (which are always valid). Like our work, their semantics is based on time points and not on temporal intervals. Yet, [4] does not consider strong and weak negation and validity intervals on logic rules. Additionally, it does not support simple queries of type 3 and type 4 and the filter condition is limited.

Note that our approach can also be applied to RDFS, as RDFS inference rules can be expressed through definite rules [7].

In [8], the authors present a general framework for representing, reasoning, and querying with annotated data on the Semantic Web. They show that their formalism can be instantiated on the temporal, fuzzy, and provenance domain. The authors associate RDF triples with their validity temporal intervals and apply the RDFS inference rules (which are

always valid). Unlike our work, their semantics is based on temporal intervals. Yet, [8] does not consider strong and weak negation and validity intervals on logic rules. Additionally, it does not support simple queries of type 4. Moreover, our query answering is more efficient, since during query answering, we directly work on maximal temporal intervals. In [8], all temporal intervals returned by the query are considered and then the maximal ones are returned. Further, our semantics are different than [8]. For example, consider the temporal RDF triples  $p(a,b) : [1990, 2000]$  and  $q(c,d) : [1995, 2010]$ . Then, according to [8], the answer to query  $p(a,b):?i \wedge q(c,d):?i' \wedge end(?i) < start(?i')$  will provide the mapping  $v$  s.t.  $v(?i)=[1990, 1994]$  and  $v(?i')=[1995, 2010]$ . In our case, we will provide no answers, since  $2000 > 1995$ .

In [9], the authors extend RDF graphs with temporal information, by associating RDF triples with their validity interval. They consider any entailment regime that can be expressed through definite rules  $A_0 \leftarrow A_1, \dots, A_n$ , where  $A_i$  is an RDF triple. Each such rule is replaced by the temporal rule  $A_0:[max(t_1, \dots, t_n), min(t'_1, \dots, t'_n)] \leftarrow A_1:[t_1, t'_1], \dots, A_n:[t_n, t'_n]$ . These rules are applied recursively, until a fixpoint is reached. Then, maximal validity temporal intervals for each derived RDF triple are produced. Yet, [9] does not consider strong and weak negation and validity intervals on logic rules. Additionally, it does not support simple temporal queries of type 4 and the filter condition is left unspecified.

Work in [10] provides a framework to support spatial and temporal analysis over semantic web data. With respect to the temporal component [10] is similar to [9], as it also computes the maximal validity temporal intervals of derived RDF triples, using the RDFS entailment rules. Yet, [10] does not consider strong and weak negation and validity intervals on logic rules.

In [11], [12], the authors extend the RDFS and ter-Horst entailment rules [13] (which extend RDFS with terms from the OWL [14] vocabulary) with temporal information. In particular, they support inference rules having the general form of these, supported by [9]. However, they do not consider a query language. Additionally, they do not consider strong and weak negation and validity intervals on logic rules.

In [15], we presented semantics for provenance and temporally annotated definite logic programs. However, [15] does not consider strong and weak negation, and reasons based on temporal intervals and not time points. The query language presented here is a restriction of the query language presented in [15] on the temporal component, with the difference that negated atoms in the queries are supported in the present work.

In [16], the authors present a temporal algebra, where the validity temporal interval of two joined relational tuples with associated temporal intervals  $i_1$  and  $i_2$  is the intersection of  $i_1$  and  $i_2$ . This temporal algebra operation is also adopted by TSQL2 [17]. In general, TSQL2 is an extension of SQL that supports temporal and non-temporal tables. It also provides a temporal relational algebra that can undertake temporal selection of data and temporal joins based on temporal intersection.

## V. CONCLUSION

In this paper, we considered extended logic programming rules, associated with their validity temporal intervals, forming a *temporally annotated logic program*.

We defined (simple) entailment and maximal entailment of a ground temporal literal  $L:i$  from a temporally annotated logic program  $C$ . Both kinds of entailment are based on Answer Set Programming. The complexities of simple and maximal entailment of ground temporal literals are provided. Additionally, we provided an algorithm that for an ELP literal or a weakly negated ELP literal  $L$  returns a list with all temporal intervals  $i$  such that a temporally annotated logic program  $C$  maximally entails  $L:i$ . Based on this algorithm, the answer of various kinds of temporal queries can be provided.

Note that we do not support operations, such as *next*, *until*, *since*, *sometimes*, and *always*, supported by temporal logic (for an overview, see [18]). Additionally, we do not support inferences such that "if something is true in one temporal interval then something else is true in another temporal interval", as supported by [19]. Yet, these works do not support the inferences made by our own model.

As future work, we plan to consider logic programs annotated over multiple domains and not just the temporal domain.

### . Appendix: Proof of Propositions

#### Proof of Proposition 1

**Hardness:** Let  $P$  be an extended logic program over a vocabulary  $V = \langle Pred, Const \rangle$ . Consider the temporally annotated logic program  $C$  over  $V$  that is derived from  $P$  by associating all rules with the validity temporal interval  $[t, t]$ . Let  $L$  be an ELP literal over  $V$ . Then,  $P \models^{ASP} L$  iff  $C \models L:[t, t]$ . In [3], it is shown that deciding if  $P \models^{ASP} L$  is (i) co-NP-complete, in the case that  $P$  does not contain variables or the number of variables of each rule of  $P$  is less than a constant and (ii) co-NEXPTIME-complete, in the general case. Therefore, deciding if a temporally annotated logic program  $C \models L:i$ , for a temporal literal  $L:i$ , is (i) co-NP-hard, in the case that  $C$  does not contain variables or the number of variables of each rule of  $C$  is less than a constant and (ii) co-NEXPTIME-hard, in the general case.

**Membership:** Guess a time point  $t$  within the temporal interval  $i$  and an interpretation  $I$  of  $C(t)$  over constants in  $Const$ . Deciding if  $I$  is an answer set of  $C(t)$  and  $I \models L$  is in (i) P, in the case that  $C(t)$  does not contain variables or the number of variables of each rule of  $C(t)$  is less than a constant and (ii) EXPTIME, in the general case [3]. Thus, deciding if  $C \models L:i$  is in (i) NP, in the case that  $C$  does not contain variables or the number of variables of each rule of  $C$  is less than a constant and (ii) NEXPTIME, in the general case. Therefore, deciding if  $C \models L:i$  is in (i) co-NP, in the case that  $C$  does not contain variables or the number of variables of each rule of  $C$  are less than a constant and (ii) co-NEXPTIME, in the general case.

#### Proof of Proposition 2

In [3], it is shown that entailment of an ELP literal or a weakly negated ELP literal  $L$  from an extended logic program  $P$ , under Answer Set Programming, is (i) co-NP-complete, in the case that  $P$  does not contain variables or the number of variables of each rule of  $P$  is less than a constant and (ii) co-NEXPTIME-complete, in the general case. Note that Algorithm 2 runs in polynomial time by calling oracles deciding if  $C(t) \models^{ASP} L$ . Therefore, the complexity of Algorithm 2 is in (i)  $P^{NP}$ , in the case that  $C$  does not contain variables or the number of variables of each rule of  $C$  is less than a constant and (ii)  $P^{NEXPTIME}$ , in the general case.

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